

AN ITERATIVE MAXIMUM EIGENVALUE METHOD FOR SQUARED DISTANCE SCALING

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ABSTRACT. Meet the abstract. This is the abstract.

1. INTRODUCTION

The problem we consider in this paper is a *metric multidimensional scaling* or *MDS* problem. In MDS the data are *dissimilarities* between n objects, and we want to map these objects into points of low-dimensional Euclidean space, in such a way that the *distances* between the points are approximately equal to the dissimilarities.

In this paper we translate the MDS objective into a squared error loss function on the squared dissimilarities. Thus we want to minimize

$$\text{sstress}(X) = \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n w_{ij} (\delta_{ij}^2 - d_{ij}^2(X))^2.$$

Here $W = \{w_{ij}\}$ and $\Delta = \{\delta_{ij}\}$, and $D(X) = \{d_{ij}(X)\}$ are the non-negative symmetric and hollow matrices of order n with, respectively, *weights* and *dissimilarities*. $D(X) = \{d_{ij}(X)\}$ is a symmetric and hollow matrix-valued function (*Euclidean*) *distances* between the rows of the $n \times p$ configuration X .

1.1. Reindexing. Some of the weights may be zero and we want to get rid of the symmetries in the loss function. First some additional notation.

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Using unit vectors e_i and e_j we can write

$$d_{ij}^2(X) = (e_i - e_j)'XX'(e_i - e_j) = \mathbf{tr} X'A_{ij}X.$$

where $A_{ij} = (e_i - e_j)(e_i - e_j)'$. We get a more compact definition by renumbering the index-pairs (i, j) with non-zero weights as $k = 1, \dots, m$, where $m \leq \binom{n}{2}$. Then

$$\mathbf{sstress}(X) = \sum_{k=1}^m w_k (\delta_k^2 - \mathbf{tr} X'A_k X)^2.$$

1.2. Using a Basis. It is convenient to choose a basis for the linear space of configurations X that interest us. This could be all of $\mathbb{R}^{n \times p}$, or it could be some subspace. Using such a basis can eliminate indeterminacy due to translation and rotation, and can be used to impose additional restrictions on the configuration [?].

Thus we write

$$X = \sum_{s=1}^p \theta_s Y_s.$$

In this new parametrization

$$\mathbf{sstress}(\theta) = \sum_{k=1}^m w_k (\delta_k^2 - \theta' C_k \theta)^2,$$

where C_k is symmetric and positive semi-definite, of order p , with elements

$$\{C_k\}_{st} = \mathbf{tr} Y_s' A_k Y_t.$$

1.3. Linear Transformation. We can suppose, without loss of generality, that the dissimilarities are scaled in such a way that

$$\sum_{k=1}^m w_k \delta_k^2 = 1.$$

If we define

$$B = \sum_{k=1}^m w_k \delta_k^2 C_k$$

we find

$$\mathbf{sstress}(\theta) = 1 - 2\theta' B \theta + \sum_{k=1}^m w_k (\theta' C_k \theta)^2.$$

Use the spectral decomposition $B = K\Lambda^2K'$. Define $E_k = \Lambda^{-\frac{1}{2}}K'C_kK\Lambda^{-\frac{1}{2}}$ and change variables with $\xi = \Lambda^{\frac{1}{2}}K\theta$. Using these new variables

$$\text{sstress}(\xi) = 1 - 2\xi'\xi + \sum_{k=1}^m w_k(\xi'E_k\xi)^2.$$

Note that we still have

$$\xi'E_k\xi = \theta'C_k\theta = \text{tr } X'A_kX = d_k^2(X).$$

1.4. **Use of Homogeneity.** Minimizing loss over ξ is the same as minimizing

$$\text{sstress}(\gamma, \zeta) = 1 - 2\gamma + \gamma^2 \sum_{k=1}^m w_k(\zeta'E_k\zeta)^2$$

over γ and $\zeta'\zeta = 1$, and this is equivalent to minimizing

$$\rho(\zeta) = \sum_{k=1}^m w_k(\zeta'E_k\zeta)^2$$

over $\zeta'\zeta = 1$. Note that ρ is convex in ζ , and homogeneous of order four, because $\rho(\gamma\zeta) = \gamma^4\rho(\zeta)$. In fact, ρ is a non-negative homogeneous polynomial of order four in ζ . Of course ρ attains its global minimum, equal to zero, at zero. For non-zero ζ we have $\rho(\zeta) = 0$ if and only if ζ is in the null-space of all E_k , which can only happen if the sum of all E_k is singular,

This is the “canonical form” for our MDS problem. We want to *minimize a weighted sum of squares of positive semi-definite quadratic forms over the unit sphere*. This problem may be of some interest in itself.

2. BASIS OF LENGTH TWO

If there are only two E_k , then we know they can both be diagonalized by a non-singular S . Say $E_1 = S\Omega S'$ and $E_2 = S\Psi S'$. Let $\kappa = S\zeta$. Then

$$\rho(\kappa) = w_1(\kappa'\Omega\kappa)^2 + w_2(\kappa'\Psi\kappa)^2$$

3. MAJORIZATION

3.1. **Algorithm.** By the AM-GM inequality

$$(\zeta' E_k \zeta)(\eta' E_k \eta) = \sqrt{(\zeta' E_k \zeta)^2 (\eta' E_k \eta)^2} \leq \frac{1}{2} \{(\zeta' E_k \zeta)^2 + (\eta' E_k \eta)^2\},$$

or

$$\frac{1}{2}(\zeta' E_k \zeta)^2 \geq (\zeta' E_k \zeta)(\eta' E_k \eta) - \frac{1}{2}(\eta' E_k \eta)^2.$$

It follows that

$$\frac{1}{2}\rho(\zeta) \geq \zeta' H(\eta) \zeta - \frac{1}{2}\rho(\eta).$$

where

$$H(\eta) = \sum_{k=1}^m w_k (\eta' E_k \eta) E_k.$$

Thus an iterative algorithm which updates $\zeta^{(v)}$ by choosing for $\zeta^{(v+1)}$ the normalized eigenvector, or one of the normalized eigenvectors, corresponding with the largest eigenvalue of $H(\zeta^{(v)})$ produces an increasing sequence $\rho^{(v)} = \rho(\zeta^{(v)})$.

If we want to spend less time in each iteration, and are prepared to use more iterations, then we can update by a single power method iteration, using

$$\zeta^{(v+1)} = \frac{H(\zeta^{(v)})\zeta^{(v)}}{\|H(\zeta^{(v)})\zeta^{(v)}\|}.$$

In any case, the increasing sequence $\rho^{(v)}$ is bounded above on the unit sphere, and thus it is convergent to, say, ρ_∞ . Because the eigenvector map is continuous, or at least closed, all accumulation points will be fixed points of the algorithmic map. At an accumulation point ζ_∞ we'll have $H(\zeta_\infty) = \rho_\infty \zeta_\infty$, and in fact ζ_∞ will be the eigenvector associated with the largest eigenvalue ρ_∞ of $H(\zeta_\infty)$.

3.2. **Rate of Convergence.**

APPENDIX A. CODE

```

1 iterSSQQ<-function(e,xi=rnorm(nrow(e)),itmax=1000,
  eps=1e-6,verbose=TRUE) {
2 xi<-xi/sqrt(sum(xi^2)); itel<-1; m<-nrow(e); fold
  <-1e6
3 repeat {
4   u<-apply(e,3,function(x) sum(outer(xi,xi)*x
  ))
5   au<-apply(u*aperm(e),c(2,3),sum)
6   ue<-eigen(au)
7   nu<-ue$vector[,m]
8   v<-apply(e,3,function(x) sum(outer(nu,nu)*x
  ))
9   av<-apply(v*aperm(e),c(2,3),sum)
10  ve<-eigen(av)
11  xi<-ve$vector[,m]
12  fnew<-sum(u*v)
13  if (verbose)
14      cat(" Iter: ",formatC(itel,digits
  =6,width=6),
15      " Eigen1: ",formatC(ue$values[m
  ],digits=6,width=12,format="
  f"),
16      " Eigen2: ",formatC(ve$values[m
  ],digits=6,width=12,format="
  f"),
17      " Sumuu: ",formatC(sum(u^2)
  ,digits=6,width=12,
  format="f"),
18      " Sumvv: ",formatC(sum(v^2)
  ,digits=6,width=12,
  format="f"),

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19         " Sumuv: ", formatC(fnew,
           digits=6,width=12,
           format="f"), "\n")
20     if ((itel == itmax) || ((fold - fnew) < eps
       )) break()
21     itel<-itel+1
22     fold<-fnew
23     }
24     print(ue$values)
25     print(ve$values)
26     return(list(x=xi,y=nu,f=fnew,u=u,iter=itel))
27 }
28
29 make.ee<-function(w,d,y) {
30   d<-d/sqrt(sum(w*d^2)); m<-length(w)
31   n<-dim(y)[1]; p<-dim(y)[3]; aa<-makeaa(n)
32   cc<-array(0,c(p,p,m))
33   for (j in 1:m) {
34     for (s in 1:p) {
35       for (t in 1:p) {
36         cc[s,t,j]<-sum(y[, ,s]*
           [,j]%*%y[, ,t]))
37       }
38     }
39   }
40   bb<-matrix(0,p,p)
41   for (i in 1:m) bb<-bb+w[i]*d[i]*cc[, ,i]
42   be<-eigen(bb)
43   bv<-be$values; bw<-sqrt(ifelse(bv<1e-10,0,1/bv))
44   by<-be$vectors; bp<-outer(bw,bw)
45   for (i in 1:m) cc[, ,i]<-crossprod(by,cc[, ,i]%*%by)
       *bp
46   bb<-matrix(0,p,p)
47   for (i in 1:m) bb<-bb+w[i]*d[i]*cc[, ,i]

```

```

48 #print(bb)
49 return(cc)
50 }
51
52 makeaa<-function (n) {
53 nn<-n*(n-1)/2; aa<-array(0,c(n,n,nn)); k<-1
54 for (i in 1:(n-1)) for (j in (i+1):n){
55     aa[i,i,k]<-aa[j,j,k]<-1
56     aa[i,j,k]<-aa[j,i,k]<-1
57     k<-k+1
58 }
59 return(aa)
60 }
61
62 basemat<-function(n) {
63 a<-matrix(rnorm(n^2),n,n)
64 a[,1]<-1
65 return(qr.Q(qr(a))[, -1])
66 }
67
68 base1<-function(n) {
69 x<-basemat(n)
70 y<-array(0,c(n,1,n-1))
71 for (i in 1:(n-1)) y[, ,i]<-x[,i]
72 return(y)
73 }
74
75 base2<-function(n) {
76 x<-basemat(n)
77 z<-rbind(0,basemat(n-1))
78 y<-array(0,c(n,2,(n-1)+(n-2))); k<-1
79 for (i in 1:(n-1)) {
80     y[,1,k]<-x[,i]
81     y[,2,k]<-0

```

```
82         k<-k+1
83     }
84     for (j in 1:(n-2)) {
85         y[,1,k]<-0
86         y[,2,k]<-z[,j]
87         k<-k+1
88     }
89     return(y)
90 }
```

REFERENCES

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